

# Teaching materials

## Deliverable 1. Platform identification

### MISCE project

Mechatronics for Improving and Standardizing Competences in Engineering



Competence: Control Engineering

Workgroup: Universidad de Castilla-La Mancha

Universitat Politècnica de València



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Mechatronics for Improving and Standardizing Competences in Engineering, MISCE  
Competence: Control Engineering  
Document: Deliverable 1. Platform  
identification

This document corresponds to the first deliverable for the competence 'Control Engineering' using  
the 'DC-motor control platform'

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Visit <https://misceproject.eu/> for more information.



## Index of contents

1	Dynamics response.....	2
2	Static gain, K.....	3
3	Time constant, T.....	4
4	Transfer function of the system .....	5



# 1 Dynamics response

In the range [-12 V, 12 V], please select 4 input tension values and represent the dynamics response and the dynamics parameters of that response in terms of angular velocity.

Input voltage value:	Input voltage value:
Input voltage value:	Input voltage value:

Figure 1. Dynamic responses of the system.

Have you filtered the velocity of the output shaft?

☐ Yes

☐ No

In affirmative case, which is the equation of the filter and its implemented code?

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## 2 Static gain, $K$

Please, include the representation of the angular velocity of the output shaft (Y-axis) against input voltage value (X-axis) and mark the region of interest (dead zone, saturation, ...).



Figure 2. Graphic representation of the steady state value of angular velocity (rad/s) vs. input voltage (V)

Which is equation of the linear regression of this relationship?

Which is the value of the static gain of the system,  $K$ ?



### 3 Time constant, T

Details the procedure to estimate the time constant of the system.



Include the graphical representation that you consider supporting the described procedure.

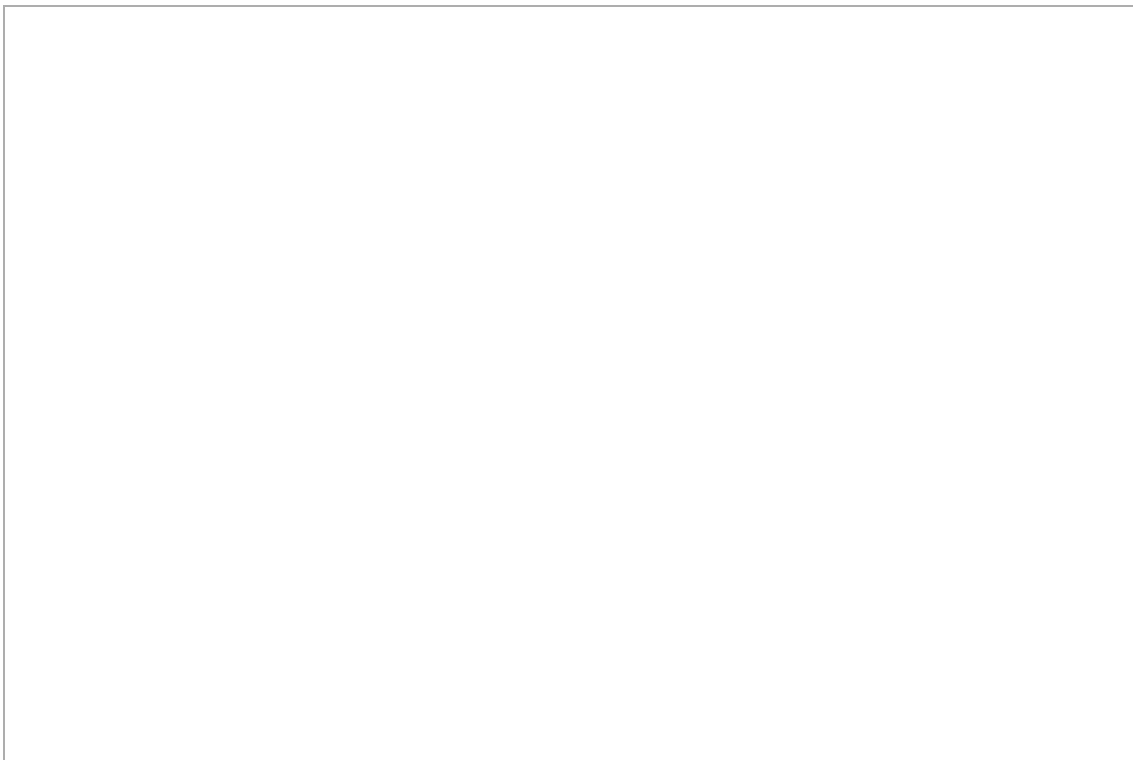


Figure 3. Graphic representation to support the identification procedure



## 4 Transfer function of the system

Please, write the equation of the transfer function of the system,  $G(s) = \frac{\theta(s)}{V(s)}$ , angular position (rad/s) vs input voltage (V).

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For two different values of input signal, please compare the experimental results with the simulated results in terms of the angular velocity.

Input voltage value:	Input voltage value:

Figure 4. Comparison results: experiments vs simulations

Include here the comments that you consider for clarifying purposes:

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